

**EAST Search History****EAST Search History (Prior Art)**

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S1	2	"20030125839"	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2010/08/06 13:59
S2	1	"10573471"	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2010/08/06 14:27
S3	27	"2006" and "62057" and JP	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2010/10/17 16:23
S4	2	"2006" and "62057" and JP and robot	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2010/10/17 16:23
S5	4	"2006062057" and JP	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2010/10/17 16:26
S6	147107	honda.as.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2010/10/17 16:31
S7	13	S6 and (robot and leg and body and (feet or foot) and joint and sensor and (weight or force or load)). clm.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2010/10/17 16:33
S8	625	(robot and leg and body and (feet or foot) and ((second or multiple or another or plurality) with joint) and sensor and (weight or force or load))	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2010/10/17 16:59
S9	746	(robot\$4 and leg and body and (feet or foot) and ((second or multiple or another or plurality) with joint) and sensor and (weight or force or load))	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2010/10/17 16:59
S10	746	robot\$4 and leg and body and (feet or foot) and ((second or multiple or another or plurality) with joint) and sensor and (weight or force or load)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2010/10/17 16:59

S11	762	robot\$4 and leg\$3 and body and (feet or foot) and ((second or multiple or another or plurality) with joint) and sensor and (weight or force or load)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2010/10/17 20:16
S12	746	robot\$4 and leg and body and (feet or foot) and ((second or multiple or another or plurality) with joint) and sensor and (weight or force or load)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2010/10/17 20:16
S13	16	S11 not S12	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2010/10/17 20:16
S14	837	robot\$4 and leg\$3 and body and (feet or foot) and ((second or multiple or another or plurality) with (joint or hinge)) and sensor and (weight or force or load)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2010/10/17 20:18
S15	91	S14 not S12	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2010/10/17 20:19
S16	6	("5114300"   "5740699"   "6330837"   "6581437"   "7118601").PN. OR ("7498758").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2010/10/17 20:26
S17	2637	700/245.ccls.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2010/10/21 23:27
S18	1819	901/1,46.ccls.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2010/10/21 23:29
S19	1074	318/568.12.ccls.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2010/10/21 23:30
S20	1283	318/568.12,568.2.ccls.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2010/10/21 23:30
S21	580	180/8.1,8.6.ccls.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2010/10/21 23:31
S22	147144	honda.as.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2010/10/21 23:40
S23	258	S22 and (robot and leg and body and (feet or foot) and joint and sensor and (weight or force or load))	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2010/10/21 23:40

S24	282	S17 and (robot and leg and body and (feet or foot) and joint and sensor and (weight or force or load))	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2010/10/21 23:41
S25	164	S17 and (robot and leg and body and (feet or foot) and joint and sensor and (weight or force or load) and ground and (multiple or plurality or second or other or another))	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2010/10/21 23:41
S26	320	(S17 or S18 or S19 or S20 or S21) and (robot and leg and body and (feet or foot) and joint and sensor and (weight or force or load) and ground and (multiple or plurality or second or other or another))	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2010/10/21 23:43

**EAST Search History (Interference)**

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S27	113865	"L1" or "L2" or "L3" or "L4" or "L5"	USPAT; UPAD	OR	ON	2010/10/21 23:31
S28	1337	700/245.ccls.	USPAT; UPAD	OR	ON	2010/10/21 23:35
S29	1069	901/1,46.ccls.	USPAT; UPAD	OR	ON	2010/10/21 23:35
S30	802	318/568.12,568.2.ccls.	USPAT; UPAD	OR	ON	2010/10/21 23:35
S31	397	180/8.1,8.6.ccls.	USPAT; UPAD	OR	ON	2010/10/21 23:35
S32	12	(S28 or S29 or S30 or S31) and (robot and leg and body and (feet or foot) and joint and sensor and (weight or force or load)).clm.	USPAT; UPAD	OR	ON	2010/10/21 23:36

10/22/2010 12:02:28 AM

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